



Designation: **F543–07<sup>e2</sup> F543–13**

## Standard Specification and Test Methods for Metallic Medical Bone Screws<sup>1</sup>

This standard is issued under the fixed designation F543; the number immediately following the designation indicates the year of original adoption or, in the case of revision, the year of last revision. A number in parentheses indicates the year of last reapproval. A superscript epsilon ( $\epsilon$ ) indicates an editorial change since the last revision or reapproval.

*This standard has been approved for use by agencies of the Department of Defense.*

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<sup>e1</sup> NOTE—Units information was editorially corrected in August 2009.

<sup>e2</sup> NOTE—Editorial changes were made throughout in March 2013.

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### 1. Scope

1.1 This specification provides requirements for materials, finish and marking, care and handling, and the acceptable dimensions and tolerances for metallic bone screws that are implanted into bone. The dimensions and tolerances in this specification are applicable only to metallic bone screws described in this specification.

1.2 This specification provides performance considerations and standard test methods for measuring mechanical properties in torsion of metallic bone screws that are implanted into bone. These test methods may also be applicable to other screws besides those whose dimensions and tolerances are specified here. The following annexes are included:

- 1.2.1 **Annex A1**—Test Method for Determining the Torsional Properties of Metallic Bone Screws.
- 1.2.2 **Annex A2**—Test Method for Driving Torque of Medical Bone Screws.
- 1.2.3 **Annex A3**—Test Method for Determining the Axial Pullout Strength of Medical Bone Screws.
- 1.2.4 **Annex A4**—Test Method for Determining the Self-Tapping Performance of Self-Tapping Medical Bone Screws.
- 1.2.5 **Annex A5**—Specifications for Type HA and Type HB Metallic Bone Screws.
- 1.2.6 **Annex A6**—Specifications for Type HC and Type HD Metallic Bone Screws.
- 1.2.7 **Annex A7**—Specifications for Metallic Bone Screw Drive Connections.

1.3 This specification is based, in part, upon ISO 5835, ISO 6475, and ISO 9268.

1.4 The values stated in SI units are to be regarded as standard. No other units of measurement are included in this standard.

1.5 Multiple test methods are included in this standard. However, it must be noted that the user is not obligated to test using all of the described methods. Instead, the user should only select test methods that are appropriate for a particular device design. In most instances, only a subset of the herein described test methods will be required.

1.6 This standard may involve the use of hazardous materials, operations, and equipment. *This standard does not purport to address all of the safety concerns, if any, associated with its use. It is the responsibility of the user of this standard to establish appropriate safety and health practices and determine the applicability of regulatory limitations prior to use.*

### 2. Referenced Documents

2.1 *ASTM Standards:*<sup>2</sup>

**E4** Practices for Force Verification of Testing Machines

**E6** Terminology Relating to Methods of Mechanical Testing

**E8** Test Methods for Tension Testing of Metallic Materials

**E122** Practice for Calculating Sample Size to Estimate, With Specified Precision, the Average for a Characteristic of a Lot or Process

**F67** Specification for Unalloyed Titanium, for Surgical Implant Applications (UNS R50250, UNS R50400, UNS R50550, UNS R50700)

**F86** Practice for Surface Preparation and Marking of Metallic Surgical Implants

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<sup>1</sup> This specification is under the jurisdiction of ASTM Committee F04 on Medical and Surgical Materials and Devices and is the direct responsibility of Subcommittee Osteosynthesis.

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<sup>2</sup> For referenced ASTM standards, visit the ASTM website, www.astm.org, or contact ASTM Customer Service at service@astm.org. For *Annual Book of ASTM Standards* volume information, refer to the standard's Document Summary page on the ASTM website.

- F116 Specification for Medical Screwdriver Bits
- F136 Specification for Wrought Titanium-6Aluminum-4Vanadium ELI (Extra Low Interstitial) Alloy for Surgical Implant Applications (UNS R56401)
- F138 Specification for Wrought 18Chromium-14Nickel-2.5Molybdenum Stainless Steel Bar and Wire for Surgical Implants (UNS S31673)
- F565 Practice for Care and Handling of Orthopedic Implants and Instruments
- F620 Specification for Titanium Alloy Forgings for Surgical Implants in the Alpha Plus Beta Condition
- F799 Specification for Cobalt-28Chromium-6Molybdenum Alloy Forgings for Surgical Implants (UNS R31537, R31538, R31539)
- F983 Practice for Permanent Marking of Orthopaedic Implant Components
- F1295 Specification for Wrought Titanium-6Aluminum-7Niobium Alloy for Surgical Implant Applications (UNS R56700)
- F1314 Specification for Wrought Nitrogen Strengthened 22 Chromium–13 Nickel–5 Manganese–2.5 Molybdenum Stainless Steel Alloy Bar and Wire for Surgical Implants (UNS S20910)
- F1472 Specification for Wrought Titanium-6Aluminum-4Vanadium Alloy for Surgical Implant Applications (UNS R56400)
- F1537 Specification for Wrought Cobalt-28Chromium-6Molybdenum Alloys for Surgical Implants (UNS R31537, UNS R31538, and UNS R31539)
- F1586 Specification for Wrought Nitrogen Strengthened 21Chromium–10Nickel–3Manganese–2.5Molybdenum Stainless Steel Alloy Bar for Surgical Implants (UNS S31675)
- F1713 Specification for Wrought Titanium-13Niobium-13Zirconium Alloy for Surgical Implant Applications (UNS R58130) (Withdrawn 0)<sup>3</sup>
- F1813 Specification for Wrought Titanium-12Molybdenum-6Zirconium-2Iron Alloy for Surgical Implant (UNS R58120)
- F1839 Specification for Rigid Polyurethane Foam for Use as a Standard Material for Testing Orthopaedic Devices and Instruments
- F2066 Specification for Wrought Titanium-15 Molybdenum Alloy for Surgical Implant Applications (UNS R58150)

2.2 ISO Standards:

- 5835 Implants for Surgery—Metal Bone Screws with Hexagonal Driver Connection, Spherical Under Surface of Head, Asymmetrical Thread—Dimensions<sup>4</sup>
- 6475 Implants for Surgery—Metal Bone Screws with Asymmetrical Thread and Spherical Under-Surface—Mechanical Requirements and Test Methods<sup>4</sup>
- 8319-1 Orthopaedic Instruments—Drive connections—Part 1: Keys for use with hexagon socket heads<sup>4</sup>
- 8319-2 Orthopaedic Instruments—Drive connections—Part 2: Screwdrivers for single slot head screws, screws with cruciate and cross-ecessed head screws<sup>4</sup>
- 9268 Implants for Surgery—Metal Bone Screws with Conical Under-Surface of Head—Dimensions<sup>4</sup>
- 10664 Hexalobular Internal Driving Feature for Bolts and Screws<sup>4</sup>

3. Terminology

3.1 Definitions—Some of the terms defined in this section are shown in Fig. 1.

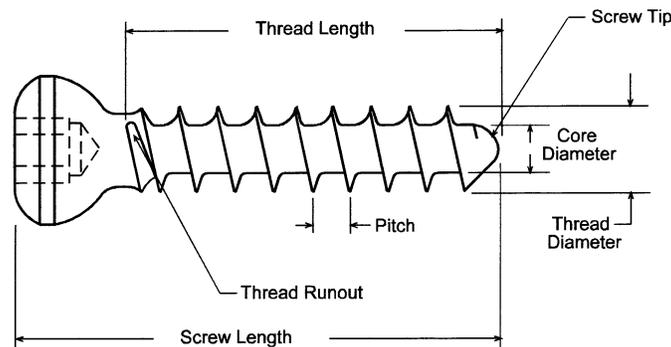


FIG. 1 Schematic of Screw Terms

3.1.1 *axial pullout strength*—the tensile force required to fail or remove a bone screw from a material into which the screw has been inserted.

<sup>3</sup> The last approved version of this historical standard is referenced on [www.astm.org](http://www.astm.org).  
<sup>4</sup> Available from American National Standards Institute, 25 W. 43rd St., 4th Floor, New York, NY 10036.

3.1.2 *breaking angle*—angle of rotation when the screw fails in torsion as demonstrated by a rapid decrease in the indicated torque.

3.1.3 *buttruss thread*—an asymmetrical thread profile characterized by a pressure flank which is nearly perpendicular to the screw axis.

3.1.4 *cancellous screw*—a screw designed primarily to gain purchase into cancellous bone. Cancellous screws typically have an HB (see 4.1.2) thread and may or may not be fully threaded.

3.1.5 *cortical screw*—a screw designed primarily to gain biocortical purchase into cortical bone. Cortical screws typically have a HA (see 4.1.1) thread and are fully threaded.

3.1.6 *core diameter*—the smallest diameter of the threaded portion of the screw measured at the thread root. This is also known as the minor diameter or root diameter.

3.1.7 *gage length*—the distance between the holding device, ~~for device~~ (for example, a split collet, collet) and the underside of the screw head.

3.1.8 *grip length*—the length of threads held fast in the split collet or other holding mechanism.

3.1.9 *insertion depth*—the threaded length as inserted into the test block.

3.1.10 *insertion torque*—the amount of torque required to overcome the frictional force between the screw and the material used for testing while driving the screw into the material.

3.1.11 *maximum torque* (N-m)—the largest value of torque recorded during the period of rotation before screw failure in torsional shear when tested in accordance with Annex A1.

3.1.12 *nontapping screw*—a screw that has a tip that does not contain a flute. Nontapping screws usually require a tap to be inserted into the pilot hole before the insertion of the screw, when used in moderate or hard bone.

3.1.13 *partially threaded screw*—a screw whose threaded portion does not extend fully from the screw point to the screw head but instead has a smooth shaft running between the head and threads.

3.1.14 *pilot hole*—the hole drilled into the bone into which the screw tip is inserted. The pilot hole is normally slightly larger than the screw's core diameter. However, if the screw is to be used to provide compression across a fracture, a portion of the pilot hole may be larger to allow for a clearance fit.

3.1.15 *pitch*—the length between the thread crests.

3.1.16 *removal torque*—the amount of torque required to overcome the frictional force between the screw and the material used for testing while removing the screw from the material (for example, counterclockwise rotation for right-hand thread).

3.1.17 *screw head*—the end of the screw which is opposite of the tip and from which the means of inserting the screw is coupled.

3.1.18 *screw length*—the overall length of the screw measured from the screw head to the screw tip.

3.1.19 *screw thread*—a helical groove on a cylindrical or conical surface. The projecting helical ridge thus formed is called a screw thread, consisting of peaks (crests) and valleys (roots).

3.1.20 *self-tapping force* (N)—the amount of axial force required to engage the self-tapping features of self-tapping style screws when tested in accordance with Annex A4.

3.1.21 *self-tapping screw*—a screw that has any number of flutes at its tip which are intended to cut the screw's thread form into the bone upon insertion.

3.1.22 *size*—an identification of a screw based on its nominal thread diameter, as defined in Section 6.

3.1.23 *solid core*—a screw that does not contain a cannulation along its longitudinal axis.

3.1.24 *thread diameter*—the largest diameter of the threaded portion of the screw measured over the thread crests. This is also known as the major diameter.

3.1.25 *thread length*—the length of the threaded portion of the screw, measured from the thread runout to the screw tip.

3.1.26 *thread runout*—the intersection of the screw thread with either the screw shaft or screw head.

3.1.27 *torsional yield strength* (N-m)—the point at which the screw reaches its proportional limit when tested in accordance with Annex A1. This will be determined by the offset method. ~~A 2°-A 2°~~ offset value will/shall be used.

#### 4. Classification

4.1 There are a large variety of medical bone screws currently in use. They may be classified by the definitions provided in Section 3. This specification currently includes information that defines the following types of screws:

4.1.1 *Type HA*—Spherical undersurface of head, shallow, asymmetrical buttruss thread, and deep screw head.

4.1.2 *Type HB*—Spherical undersurface of head, deep, asymmetrical buttruss thread, and shallow screw head.

4.1.3 *Type HC*—Conical undersurface of head, symmetrical thread.

4.1.4 *Type HD*—Conical undersurface of head, asymmetrical thread.

## 5. Material

5.1 Screws shall be fabricated from ~~one of the following materials:~~ a metallic material intended for surgical implant applications, and having ASTM medical material. In addition, the materials shall be biocompatible for the intended application.

- 5.1.1 ~~Stainless steel alloy (Specification F138):~~
- 5.1.2 ~~Nitrogen-strengthened stainless steel alloy (Specifications F1314 and F1586):~~
- 5.1.3 ~~Unalloyed titanium (Specification F67):~~
- 5.1.4 ~~Titanium-aluminum-vanadium alloy (Specifications F136, F620, and F1472):~~
- 5.1.5 ~~Titanium-aluminum-niobium alloy (Specification F1295):~~
- 5.1.6 ~~Titanium-niobium-zirconium alloy (Specification F1713):~~
- 5.1.7 ~~Cobalt-chromium-molybdenum alloy (Specifications F799 and F1537):~~
- 5.1.8 ~~Titanium-molybdenum-zirconium-iron alloy (Specification F1813):~~

## 6. Dimensions and Tolerances

6.1 There are many types of metallic bone screw designs available, so a complete list of dimensions and tolerances for all screws covered by this specification is unfeasible. However, this specification does provide required dimensions and tolerances for four types of screws as classified in 4.1. Screws conforming to this specification, and designated HA, HB, HC, or HD screws, shall be fabricated in accordance with the dimensions and tolerances described in Annex A5 and Annex A6, respectively.

## 7. Finish and Marking

- 7.1 The screw shall be free from nicks, dents, burrs, and scratches when examined in accordance with Practice F86.
- 7.2 When size permits, the following information should be legibly marked on the head of the screw (in order of preference):
  - 7.2.1 Manufacturer's name or logo,
  - 7.2.2 *Screw Size*—If a screw is manufactured in accordance with ASTM or ISO specifications, the ASTM or ISO designation should be provided,
  - 7.2.3 Material,
  - 7.2.4 Catalog number, and
  - 7.2.5 Manufacturing lot number.
- 7.3 Screws shall be marked in accordance with Practice F983, unless otherwise specified in 7.2, in a manner such that the mechanical integrity of the screw is not compromised.

## 8. Care and Handling

- 8.1 Screws should be cared for and handled in accordance with Practice F565, as appropriate.

## 9. Driving Instruments

9.1 A variety of screwdrivers exist for the insertion and removal of bone screws. The classification and dimensions for various screw-drive recesses currently used in the medical industry are documented in Annex A7. Specification F116 provides related dimensional information for several types of medical screwdrivers.

9.2 Screws conforming to this specification, and designated HA, HB, HC, or HD screws, shall be manufactured with drive recesses that conform to the requirements specified in Annex A5 and Annex A6, respectively.

## 10. Performance Considerations and Test Methods

10.1 The following properties may be important when determining the suitability of a screw for a particular application. However, the test methods referenced as follows may not be appropriate for all types of implant applications. The user is cautioned to consider the appropriateness of the test methods in view of the devices being tested and their potential application.

10.1.1 *Torsional Strength*—This test method is an important parameter to prevent screw breakage during insertion or removal. The torsional strength shall be determined using the test methods described in Annex A1.

10.1.2 *Breaking Angle*—This test method provides a measure of the ductility of the screw when undergoing a torsional moment. A screw with a greater breaking angle may provide an earlier tactile warning to the surgeon that the screw is reaching its maximum torsional strength. The breaking angle shall be determined using the test methods described in Annex A1.

10.1.3 *Axial Pullout Strength*—This test method may be an important parameter if the screw is subjected to axial tensile forces, or if the screw is fixed into poor quality or osteoporotic bone. The pullout strength may be determined using the test methods described in Annex A3.

10.1.4 *Insertion Torque*—This test method may be an important parameter to avoid failure of the screw during insertion and to ensure that the screw may be easily inserted by the surgeon. The insertion torque should be much less than torsional yield strength of the screw and of the appropriate screwdriver bit. The insertion torque may be determined using the test methods described in Annex A2.

10.1.5 *Removal Torque*—This test method may be an important parameter to avoid failure of the screw during removal and to ensure that the screw may be easily removed by the surgeon. The removal torque should be much less than torsional yield strength of the screw and of the appropriate screwdriver bit. The removal torque may be determined using the test methods described in Annex A2.

10.1.6 *Self-Tapping Force*—This test method may be an important parameter to ensure that the screw may be easily inserted by the surgeon, particularly if the screw is fixed in poor quality or osteoporotic bone. The self-tapping force may be determined using the test method described in Annex A4.

**11. Performance Requirements**

11.1 Screws shall meet the mechanical performance requirements specified in its associated specification annex.

**12. Keywords**

12.1 bone screw; dimensions; insertion; performance requirements; pullout; static; test methods; torsion

**ANNEXES**

(Mandatory Information)

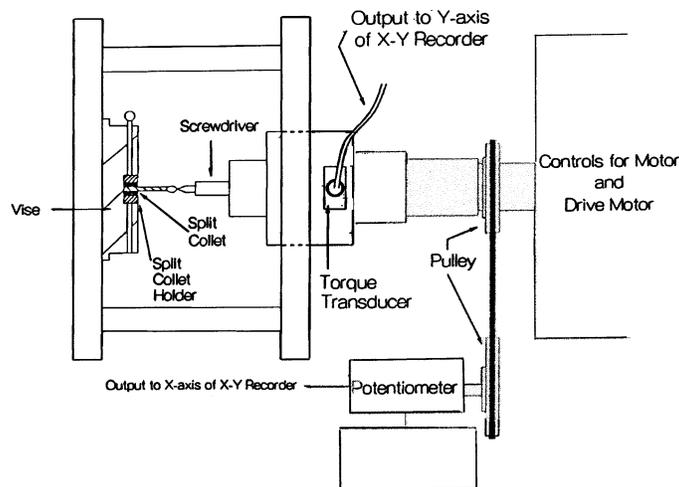
**A1. TEST METHOD FOR DETERMINING THE TORSIONAL PROPERTIES OF METALLIC BONE SCREWS**

**A1.1. Significance and Use**

A1.1.1 This test method is used to measure the torsional yield strength, maximum torque, and breaking angle of the bone screw under standard conditions. The results obtained in this test method are not intended to predict the torque encountered while inserting or removing a bone screw in human or animal bone. This test method is intended only to measure the uniformity of the product tested or to compare the mechanical properties of different, yet similarly sized, products.

**A1.2. Apparatus**

A1.2.1 *Testing Fixture*—The torsion testing apparatus that is to be used for applying the required torque to the specimen shall be calibrated for the range of torques and rotational displacements used in the determination.<sup>5</sup> A suitable testing fixture for the torsional yield strength-maximum torque-breaking angle test is illustrated in Fig. A1.1.



**FIG. A1.1 Test Apparatus for Determination of Torsional Breaking Force and Breaking Angle**

A1.2.1.1 *Test Speed*—The torsional force shall be applied at a constant rate of 1 to 5 r/min.

<sup>5</sup> At the time that this specification was approved, no standard test method for the verification of torsion machines or transducers has been accepted. The user is urged to review Terminology E6 and Test Methods E8 for general guidance.

A1.2.1.2 *Torque Transducer*—A transducer to translate the applied torque into an electrical signal amenable to continuous recording, calibrated over the range of torques, both in the clockwise and counterclockwise rotation, to be encountered in the test method, shall be provided.

A1.2.1.3 *Torsional Displacement Transducer*—A transducer to translate the angle of twist into an electrical signal amenable to continuous recording, calibrated over the range of angles to be encountered in the test and an accuracy of  $\pm 0.3^\circ$ , both in the clockwise and counterclockwise rotation, shall be provided.

A1.2.1.4 *Specimen Holder*—A mechanical device to clamp onto the bone screw to prevent its rotation while being stressed without significantly damaging its mechanical integrity shall be provided. One such method is to insert a threaded stopper into the opposite side of a test block. The test block for this holding mechanism will accommodate the insertion of a threaded stopper on the other side of the test block. The threaded stopper will prevent the screw from being completely inserted into the test block and will allow the torsional strength of the screw to be measured. This holder will be modified according to the size of the testing specimen so that the gage length of the specimen will be as outlined in A1.3.1.

A1.2.1.5 *Recorder*—The data recorder shall be suitable to continuously record torque versus angle of rotation, calibrated in units of Newton-metres for torque and degrees for angle of rotation. The value of torque shall have a resolution of 5 % of torsional yield strength. The angular displacement scale shall have a minimum sensitivity so as to enable an accurate offset measurement capability for a  $2^\circ$  angular displacement (see A1.3.3).

A1.2.2 *Test Specimen*—The test specimen shall be a completely fabricated and finished bone screw.

### A1.3. Procedure

A1.3.1 *Torsional Yield Strength, Maximum Torque, and Breaking Angle*—Place the specimen in the holding device so that five threads, below the head of the screw, are exposed outside the holding device (for example, split collet, and so forth). If the test specimen cannot accommodate this setup because the screw is too small or is partially threaded, alternate procedures may be used. For fully threaded screws that are too small, the gage length of the specimen should represent 20 % of the threaded portion of the test specimen. For partially threaded screws, a large enough portion of the screw thread should be gripped to firmly secure the screw so that it does not rotate when under torsional load. There are no specific requirements on the gage length or the grip length in this case; however, at least one full thread shall be exposed, if possible. Since the gage length and grip length can vary for these screws, the only requirement is that both be reported.

A1.3.2 The gage length or grip length should be kept the same length for test screws of similar design. If a split collet and collet holder are used, the following test method is appropriate: ~~place~~ appropriate. Place the split collet in the collet holder. Clamp the split collet and holder in the vise. The clamping force of the vise should be sufficient to prevent rotation of the screw or the split collet. Drive the specimen in the direction of insertion, using an appropriate size and configured screwdriver bit, by applying a torsional force. If an axial load is required to maintain the screwdriver bit in the screw head, its value should be noted. The torque wrench shall be driven at a rate of 1 to 5 ~~r/min~~ revolutions/min (r/min).

NOTE A1.1—The simultaneous use of two chart recorders may simplify the ability to measure torsional yield strength accurately by the offset method. One chart recorder with an angular displacement scale or sensitivity of  $50^\circ/\text{cm}$  is convenient for measuring maximum torque and breaking angle. A second chart recorder with an angular displacement scale or sensitivity of  $10^\circ/\text{cm}$  or less is suggested to provide accurate offset measurement capability for measuring a  $2^\circ$  angular displacement. Alternatively, one chart recorder and a digital storage oscilloscope may be used.

A1.3.3 The torsional yield strength will be determined by the offset method (Fig. A1.2), using the torque versus angle of rotation curve produced in A1.3.1 and A1.3.2.

A1.3.3.1 On the torque versus angle of rotation curve, locate Point *m* equal to a rotation of  $2^\circ$ . Draw *mn* parallel to *OA*, and locate *b*, the intersection of *mn* with the torque versus angle of rotation curve. Torque *B* is defined as the torsional yield strength.

A1.3.3.2 The maximum torque is determined by the largest value of torque on the torque versus angle of rotation curve.

A1.3.3.3 The breaking angle is determined from the torque versus angle plot shown in Fig. A1.3. The breaking angle is defined as the point at which the torque portion of the curve demonstrates its most rapid descent (negative slope) to total failure. The breaking angle (B.A.) is determined as the intersection of the two tangents (*D* and *E*) shown in Fig. A1.3. Line *E* is a tangent to

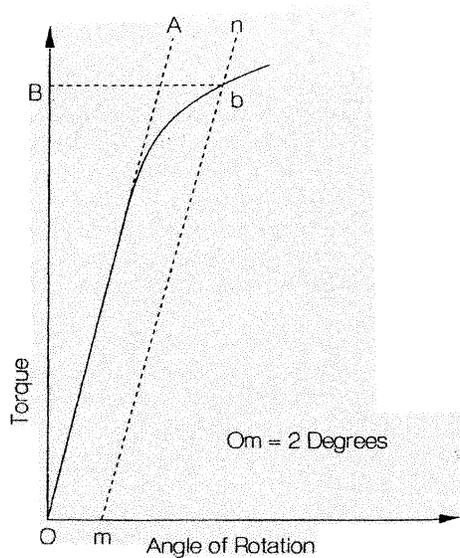


FIG. A1.2 Typical Torque Versus Angle of Rotation Curve

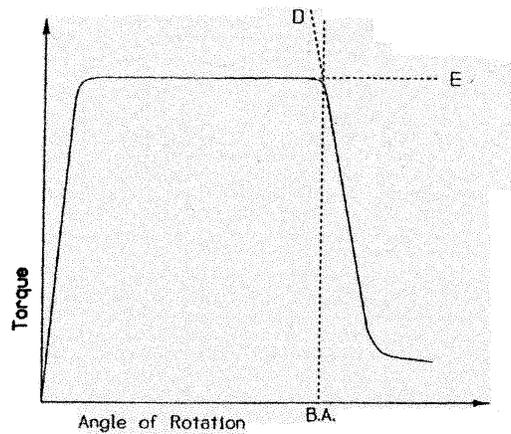


FIG. A1.3 Typical Plot of Torque Versus Torsion Angle

the horizontal portion of the curve which represents maximum torque. Line *D* is drawn at the curve's most rapid descent. The intersection of these two lines is the breaking angle (B.A.) and is recorded to the nearest 10°.

#### A1.4. Report

A1.4.1 Report the following information for each specimen tested:

A1.4.1.1 *Screw Identification*—Reference any applicable ASTM or ISO specification that may apply to the specimen. If specifications do not exist, provide head form, thread form, major and minor diameter, thread pitch, overall screw length, head and shank (unthreaded portion of the screw excluding the head) length, and type of screw point.

A1.4.1.2 Screw chemical composition.

A1.4.1.3 Surface finish.

A1.4.1.4 Gage length.

A1.4.1.5 Torsional yield strength.

A1.4.1.6 Maximum torque.

A1.4.1.7 Breaking angle.

A1.4.1.8 Torque versus angle of rotation plot.

A1.4.1.9 The size of the exposed portion of the screwdriver (that is, the length and diameter relative to the tested screw) or the angular deformation of the screwdriver assembly at maximum torque.

A1.4.1.10 *Grip Length*—Does not have to be reported for a fully threaded screw of ASTM or ISO specification whose overall length is given.

A1.4.1.11 *Fracture Location*—The location can be specified by listing the number of threads below the head at which the screw fails or by measuring the distance below the head to the approximate fracture point.

**A1.5. Precision and Bias**

A1.5.1 Data establishing the precision and bias to be expected from this test method have not yet been obtained.

**A2. TEST METHOD FOR DRIVING TORQUE OF MEDICAL BONE SCREWS**

**A2.1. Significance and Use**

A2.1.1 This test method is used to measure the torque required to drive a bone screw into a standard material. The results obtained in this test method bear no direct correlation to the insertion torque required to insert the subject bone screw in human or animal bone. This test method is used only for ~~purposes~~ the purpose of maintaining the uniformity of the product tested.

**A2.2. Apparatus**

A2.2.1 *Testing Fixture*—A suitable test fixture as shown in Fig. A2.1 may be used for the insertion-removal torque tests.<sup>5</sup> This fixture shall incorporate the test block material that conforms to Specification F1839, test block clamp, drill bushing, and bushing support depicted. It shall be sufficiently rigid to not deflect or deform under the conditions of loading encountered during the test.

A2.2.1.1 *Torque Transducer*—A transducer to translate the applied torque into an electrical signal amenable to continuous recording, calibrated over the range of torques, both in the clockwise and counterclockwise rotation, to be encountered in the test shall be provided.

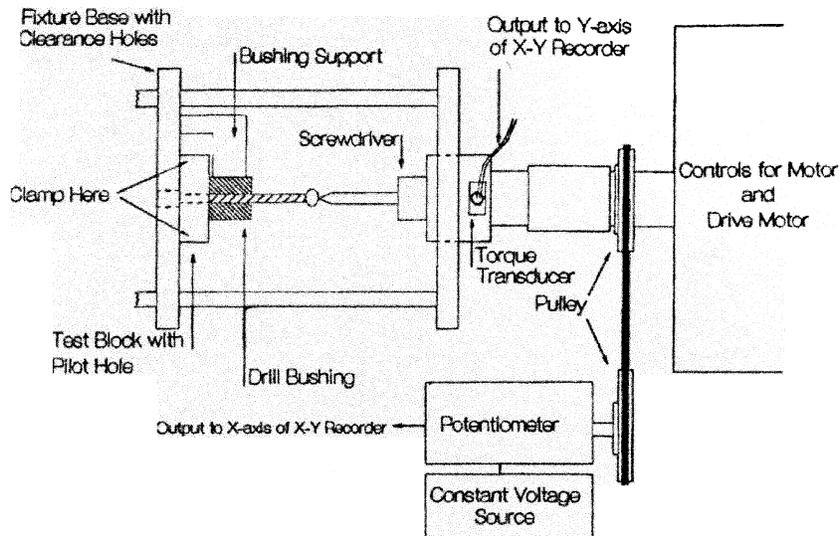


FIG. A2.1 Schematic of Test Apparatus for Driving Force

**A2.2.1.2 Torsional Displacement Transducer**—A transducer to translate the angle of twist into an electrical signal amenable to continuous recording, calibrated in a manner similar to Practices **E4** over the range of angles to be encountered in the test to an accuracy of  $\pm 0.3^\circ$ , both in the clockwise and counterclockwise rotation, shall be provided.

**A2.2.1.3 Data Recorder**—The data recorder shall be suitable to record torque versus angle of rotation continuously, calibrated in units of newton-metres for torque and degrees for angle of rotation. The value of torque shall have a resolution of 10 % of the maximum measured torque. The angular displacement scale shall have sensitivity such that at least four revolutions can be recorded and displayed.

**A2.2.1.4 Bushing**—A suitable replaceable bushing, fabricated from material that conforms to Specification **F1839**, shall be incorporated into the testing fixture. This bushing shall be of sufficient length and rigidity to ensure that specimens are driven into the test block normal to the top surface of the test block. The bore of the bushing shall be of such dimension as to ensure guidance of the test specimen with minimum frictional resistance between the major diameter of the test specimen and the bore of the bushing. Worn bushings shall be discarded and replaced with new bushings before conducting the test.

**A2.2.1.5 Test Block Clamp**—A clamp or holding device shall be incorporated into the testing fixture. This holding device shall maintain the drilled pilot hole in the test block in line with the test specimen. The holding device shall not deform the test block during clamping of the test block or performance of the test.

**A2.2.1.6 Test Specimen**—The test specimen shall be a completely fabricated, finished, and sterilized bone screw of sufficient length to transverse the bushing and test block.

**A2.2.1.7 Test Block**—The test block shall be fabricated from a uniform material that conforms to Specification **F1839**. The choice of appropriate foam density for this test is at the discretion of the user. See Section 8.6.2 of **F1839** for additional information. To accommodate the requirements of the pilot hole as described in **A2.2.1.8**, the smallest dimension of the test block's surface shall be greater than 10× the diameter of the screw under test. The top and bottom surfaces shall be flat, smooth, and parallel (within  $\pm 0.4$  mm) as required to ensure that the test block will be supported in the fixture with the top surface at an angle of  $90^\circ$  to the centerline of the test specimen. The edges of the test block shall be of such contour or squareness as required to ensure that the test block clamp shall hold the test block free of relative motion without deformation of the test block during clamping or testing. The test block thickness shall be not less than 4.8 mm.

**A2.2.1.8 Pilot Holes in Test Block**—Pilot holes shall be drilled in the test block for insertion and removal of the test specimen. The drill size used shall be that specified by the screw manufacturer, for the size screw being tested. If specified by the screw manufacturer, the specified sized tap shall be used to tap the pilot hole before testing. The holes shall be drilled at  $90^\circ$  to the top surface of the test block. The holes shall be drilled straight and true, free of taper, bell mouth, or barrel shape. If there are multiple holes in one test block, the pilot holes shall be spaced sufficiently far away from test block edges so that testing does not deform the test block edges. Spacing should have a minimum distance of 5× the diameter of the screw. When the test block is inserted into the test fixture (**Fig. A2.1**), the pilot hole, screw, and screwdriver shall be on the same axis.

### **A2.3. Sampling**

**A2.3.1** Representative random samples may be taken from each lot or processing quantity in accordance with Practice **E122**.

### **A2.4. Procedure**

**A2.4.1 Insertion and Removal Torque**—Place the specimen in the test fixture as illustrated in **Fig. A2.1**. Drive the specimen into the test block, using the appropriate size and configured screwdriver bit, by applying a torsional force at a rate of 1 to 5 r/min, to the head of the specimen with the motor-driven torque wrench. The insertion torque shall be the maximum reading recorded during the initial four revolutions of the specimen. The removal torque ~~will~~ shall be measured by reversing the direction of rotation and recording the maximum torque recorded during the four revolutions required to remove the screw from the test block. Values should be reported in ~~newton-metres-n~~ Newton-metres. A 1.14-kgf or less axial load should be used to maintain the screwdriver bit in the screw head during both the insertion and removal procedures. If a larger axial load is applied, this load shall be recorded on the report form. This load may be measured by any appropriate method.

### **A2.5. Report**

**A2.5.1** The report shall include the following for each specimen tested. (All standards units for reporting shall be in SI units.)

A2.5.1.1 *Screw Identification*—Reference any applicable ASTM or ISO standard specification that may apply to the specimen. If specifications do not exist, provide head form, thread form, major and minor diameter, thread pitch, overall screw length, head and shank (unthreaded portion of the screw excluding the head) length, and type of screw point.

A2.5.1.2 Screw chemical composition.

A2.5.1.3 Surface finish.

A2.5.1.4 Insertion torque.

A2.5.1.4.1 Axial load required.

A2.5.1.4.2 Insertion depth (may be calculated or measured).

A2.5.1.4.3 Specification of whether the pilot holes were or were not pretapped, if so, specifications of the tap size, tap diameter, and tap ~~depth~~depth shall be reported.

A2.5.1.4.4 Insertion test speed if outside the range specified in A2.4.1.

A2.5.1.5 Removal torque.

A2.5.1.5.1 Axial load required.

A2.5.1.5.2 Insertion test speed if outside the range specified in A2.4.1.

A2.5.1.6 *Test Block Material Description*—Specification F1839 grade. For bushing material that does not conform to Specification F1839, provide

A2.5.1.6.1 Trade name.

A2.5.1.6.2 Composition.

A2.5.1.6.3 Density.

A2.5.1.6.4 Tensile strength.

A2.5.1.6.5 Compression strength.

A2.5.1.6.6 Shear strength.

## A2.6. Precision and Bias

A2.6.1 Data establishing the precision and accuracy to be expected from this test method have not yet been obtained.

**A3. TEST METHOD FOR DETERMINING THE AXIAL PULLOUT STRENGTH OF MEDICAL BONE SCREWS**

**A3.1. Significance and Use**

A3.1.1 This test method is used to measure the axial tensile force required to fail or remove a bone screw from a defined material. The results obtained in this test method are not intended to predict the force required to remove the subject bone screw from human or animal bone. This test method is intended only to measure the uniformity of the products tested or to compare the strength of different products.

A3.1.2 This test method may not be appropriate for all types of implant applications. The user is cautioned to consider the appropriateness of the method in view of the materials being tested and their potential application.

**A3.2. Apparatus**

A3.2.1 *Test Fixture*—Machines used for testing the axial pull-out strength of screws shall conform to the requirements of Practices E4. A suitable test fixture as shown in Fig. A3.1 may be used for testing. This fixture shall incorporate the test block material which conforms to Specification F1839, test block clamp, drill bushing, and bushing support depicted in the insertion torque test method, Annex A2. In addition to these requirements, the test block clamp and bushing support should be sufficiently rigid such that deflection under the required loading conditions is negligible. The test block clamp should have a minimum grip span of five times the major diameter of the bone screw with the screw centered between the grips. The grip span should be consistent throughout testing.

A3.2.2 *Test Block*—The test block shall be fabricated from a uniform material that conforms to Specification F1839. The choice of appropriate foam density for this test is at the discretion of the user. See Section 8.6.2 of F1839 for additional information. The top and bottom surfaces shall be flat, smooth, and parallel (within  $\pm 0.4$  mm) as required to ensure that the test block will be supported in the fixture with the top surface at an angle of  $90^\circ$  to the centerline of the test specimen. The edges of the test block shall be of such contour or squareness as required to ensure that the test block clamp shall hold the test block free of relative motion without deformation of the test block during clamping or testing. The test block thickness shall be not less than 20 mm.

A3.2.3 *Data Acquisition Device*—The data recorder shall be suitable to continuously record load versus load fixture displacement.

A3.2.4 *Load Frame*—Machines used for testing shall conform to the requirements of Practices E4. The loads used for the test method shall be within the loading range of the test machine as defined in Practices E4.

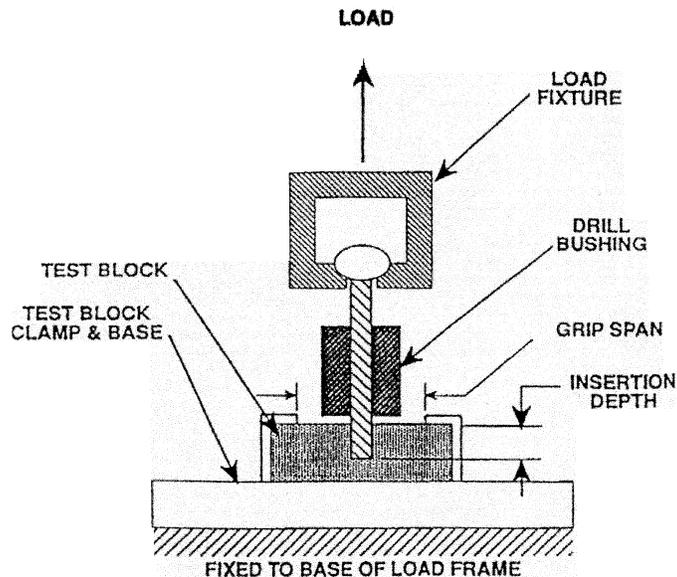


FIG. A3.1 Schematic of Test Apparatus for Pullout Strength

A3.2.5 *Load Fixture*—A suitable fixture shall be used to place a tensile load on the bone screw. The load shall be transferred through the head of the screw and should be aligned with the screw's longitudinal axis. The fixture shall have a slot to capture the head of the screw without contact being made with the screw's shaft. To ensure proper alignment, the slot shall have a spherical recess into which the screw head can be seated directly under the applied load.

### A3.3. Sampling, Test Specimens, and Test Units

A3.3.1 All test components shall be representative of implant quality products.

### A3.4. Procedure

A3.4.1 *Insertion of the Test Specimen*—The bone screws shall be inserted into the standard material in accordance with the insertion torque test method, [Annex A2](#). The screws shall be inserted at a rate of 3 r/min to a depth of 20 mm. For fully threaded screws with threaded lengths less than 20 mm, the insertion depth should be 60 % of the threaded length of the screw. Partially threaded bone screws should have all threads inserted into the standard material.

A3.4.2 *Axial Pullout Strength of the Test Specimen*—The test block and test block clamp depicted in [Annex A2](#) shall be fixed to the base of the load frame so that the longitudinal axis of the screw is aligned with the direction of the applied load. The screw's head shall be placed in the slot of the load fixture and seated in the spherical recess. The load fixture shall then be attached to the load frame. A tensile load shall be applied to the test specimen at a rate of 5 mm/min until the screw fails or releases from the test block. Load (newtons) versus load fixture displacement (millimetres) shall be recorded on a data acquisition device, noting the maximum load applied and the mode of failure (screw shaft, screw threads, or material failure).

### A3.5. Calculation or Interpretation of Results

A3.5.1 *Axial Pullout Strength*—Determine the axial pullout strength (~~newtons~~) (in Newtons) of the test specimen from the load-displacement curve. The maximum load is reached during the test method.

### A3.6. Report

A3.6.1 Report the following information:

A3.6.1.1 *Screw Identification*—Reference any applicable ASTM or ISO standard specification that may apply to the specimen. If specifications do not exist, provide head form, thread form, helix angle, major and minor diameter, thread pitch, overall screw length, head and shank length, length of threaded portion of shank for partially threaded screws, and type of screw point.

A3.6.1.2 Screw chemical composition.

A3.6.1.3 Surface finish.

A3.6.1.4 Axial pullout strength (as defined in [3.1.1](#)).

A3.6.1.5 Grip span.

A3.6.1.6 Insertion depth.

A3.6.1.7 Test block thickness.

A3.6.1.8 Mode of failure.

A3.6.1.9 *Test Block Material Description*—Specification [F1839](#) grade or density. For materials that do not conform to [F1839](#), provide the following information and the appropriate test methods used to determine the properties of the test block material:

A3.6.1.9.1 Trade name,

A3.6.1.9.2 Composition,

A3.6.1.9.3 Density,

A3.6.1.9.4 Tensile strength,

A3.6.1.9.5 Compression strength, and

A3.6.1.9.6 Shear strength.

**A3.7. Precision and Bias**

A3.7.1 Data establishing the precision and accuracy to be expected from this test method have not yet been obtained.

**A4. TEST METHOD FOR DETERMINING THE SELF-TAPPING PERFORMANCE OF SELF-TAPPING MEDICAL BONE SCREWS**

**A4.1 Significance and Use**

A4.1.1 This test method is used to determine the axial compression load (force) required to engage the self-tapping feature of self-tapping medical bone screws into a standard material. The results obtained in this test method bear no direct correlation to the axial force required to insert the subject bone screw in human or animal bone. This test method is used only to measure uniformity of the product tested or to compare the performance of different, yet similarly sized, products. This test method is not applicable to “self-drilling” or “self-drilling/self-tapping” styles of medical bone screws.

**A4.2 Apparatus**

A4.2.1 *Testing Apparatus*—A schematic for the axial self-tapping force test apparatus is illustrated in Fig. A4.1. The apparatus shall provide a variable speed motor capable of continuously driving a spindle. The spindle shall be capable of a continuous rotation as well as axial translation to allow variable force on the test specimen. The apparatus and spindle shall be sufficiently rigid to neither deflect nor deform under the conditions of loading encountered during the test. The apparatus shall incorporate a test block clamp for purposespurpose of rigidly fixing a test block. The apparatus shall be capable of continuously monitoring and recording the force, torque, and axial displacement of the specimen. The apparatus shall be calibrated for the range of forces, torques, and linear displacements used in the determination.

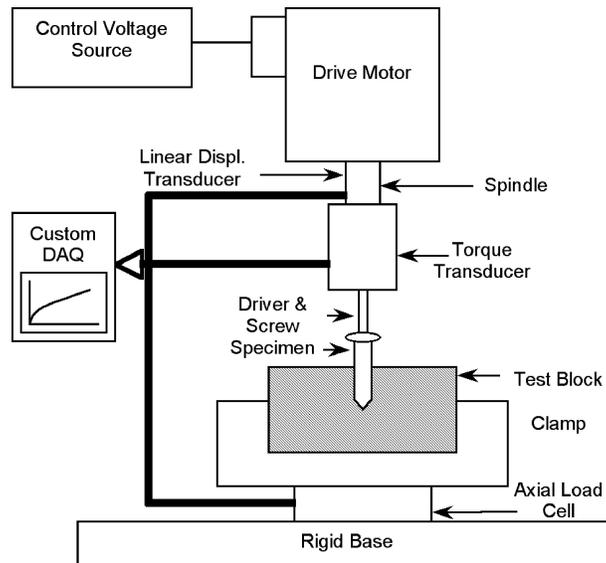


FIG. A4.1 Schematic of Test Apparatus for Determination of Self-Tapping Force

A4.2.2 *Compression Load Cell*—A transducer to translate the applied axial force into an electrical signal suitable for continuous recording and calibrated over the range of forces to be encountered in the test method, shall be provided. The load cell should have an accuracy of 0.5 % of full-scale output and allow measurement resolution of  $\pm 1.0$  N.

A4.2.3 *Torque Transducer*—A transducer to translate the applied torque into an electrical signal suitable for continuous recording and calibrated over the range of torques, both in clockwise and counterclockwise rotation, to be encountered in the test method, shall be provided. The torque transducer should have an accuracy of 0.5 % of full-scale output and allow measurement resolution of  $\pm 0.10$  N-m.

NOTE A4.1—A combination compressive load and torque transducer is suitable for this application provided the transducer meets the specifications detailed in A4.2.2 and A4.2.3.

A4.2.4 *Linear Displacement Transducer*—A transducer to translate the axial displacement of the test apparatus' spindle into an electrical signal suitable for continuous recording and calibrated over the range of displacements to be encountered in the test method, shall be provided. The displacement transducer should have an accuracy of 1 % of full scale and allow a measurement resolution of  $\pm 0.5$  mm.

A4.2.5 *Test Block Clamp*—A clamp or holding device shall be incorporated into the testing fixture. This holding device shall maintain the drilled pilot hole in the test block in line with the test specimen. The holding device shall be sufficiently rigid to neither deflect nor deform under the conditions of loading encountered during the test and yet not deform the test block during clamping of the test block or performance of the test.

A4.2.6 *Test Block*—The test block shall be fabricated from a uniform material that conforms to Specification F1839. The top and bottom surfaces shall be flat, smooth, and parallel (within 0.4 mm) as required to ensure that the test block will be supported in the fixture with the top surface at an angle of 90° to the centerline of the test specimen. The edges of the test block shall be of such contour or squareness as required to ensure that the test block clamp shall hold the test block free of relative motion without deformation of the test block during clamping or testing. The test block thickness shall be not less than 25 mm.

A4.2.7 *Pilot Holes in Test Block*—Pilot holes shall be drilled in the test block for insertion and removal of the test specimen. The drill size used shall be that specified by the screw manufacturer for the size screw being tested. The holes shall be drilled at 90° to the top surface of the test block. The holes shall be drilled straight and true, free of taper, bell mouth, or barrel shape. The holes should be drilled completely through the test block and all particulate debris removed prior to inserting the test specimen. If there are multiple holes in one test block, the pilot holes shall be spaced sufficiently far away from test block edges so that testing does not deform test block edges. Spacing should have a minimum distance as recommended in A2.2.1.8. When the test block is inserted into the test fixture (Fig. A4.1), the pilot hole, screw, and screwdriver shall be on the same axis.

A4.2.8 *Test Specimen*—The test specimen shall be a completely fabricated and finished bone screw of sufficient length to allow completion of the test.

A4.2.9 *Recorder*—The data recorder shall be suitable to record continuously, at a minimum rate of 10 Hz, axial compression force, torque, and axial spindle displacement. The recorder shall be capable of recording two *Y* axes simultaneously (force and torque to *Y* Axis 1 and displacement to *Y* Axis 2) versus time (*X* axis), calibrated in units of Newtons for force, Newton-metres for torque, and millimetres for displacement. The value of force and torque should have a resolution of 0.5 % of full-scale output and sensitivity so as to enable an accurate recording capability of a minimum of 1.0 N and 0.10 N-m, respectively. The value of torque shall have a resolution of 0.5 % of full-scale output. The linear displacement scale should have a minimum sensitivity so as to enable an accurate recording capability for 0.5 mm.

A4.2.10 *Test Speed*—The torsional force shall be applied at a constant rate of 30 r/min. The axial compression force shall be applied at a constant rate of approximately 2 N/s. The torsional test speed has been selected to represent the clinical situation of hand-driven screws. The axial load rate has been selected to allow easy identification and reaction to the unique self-tap events on the data output recorder. Other test speeds and load rates can be used provided they are justified and reported. All comparative tests shall be performed at the same test speeds.

### A4.3 Sampling

A4.3.1 Representative random samples may be taken from each lot or processing quantity in accordance with Practice E122.

### A4.4 Procedure

A4.4.1 *Self-Tapping Force*—The pre-drilled test block is rigidly fixed in the test block clamp device shown in Fig. A1.1. The appropriate-sized screwdriver (“driver”) is inserted into the spindle and the alignment of the pilot hole with the driver is verified. The self-tapping bone screw specimen is then pre-assembled (“loaded”) onto the driver. The specimen/driver assembly is then lowered via the spindle into the pilot hole and the axial displacement of the spindle adjusted to achieve a maximum preload of 1.0 N to maintain screw-to-screwdriver engagement.

A4.4.2 The specimen is then driven by the test apparatus at a constant rotational rate of 30 ~~r/min~~ revolutions/minute. The axial force, torque, and displacement channels on the data recorder are monitored simultaneously while the axial force is increased at a rate of approximately 2.0 N/s ( $\pm$  1.0 N/s). The axial compression force ~~will~~ shall continue to be increased until the self-tapping features of the screw engage the test block as indicated by a marked increase in torque and axial displacement are ~~noted~~ observed as shown in Fig. A4.2.

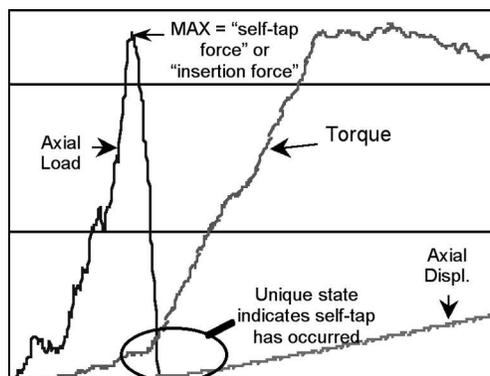
A4.4.3 This unique combination signifies the engagement of the self-tapping features of the bone screw into the test material and the onset of “self-tap.” At this moment, the increase in axial force should be discontinued and the load level at which self-tap was first noted maintained (that is, “load and hold”) while simultaneously monitoring the specimen to ensure the continued self-advance into the test block as noted by the continually increasing torque and axial displacement. (Note that in some instances the axial force may decrease at the onset of self-tap, as shown in Fig. A4.2, indicating self-advancement of the specimen into the test block without the need for continuous, applied force. Thus, during this phase of the test, the axial force serves only to maintain driver-to-screw engagement.)

A4.4.4 A total of five complete revolutions should be achieved after the onset of self-tap to be considered a valid specimen. The maximum axial force achieved at the onset of self-tap shall be reported as the “self-tap force.” Values should be reported in Newtons. On occasion, the specimen will self-tap and then cease advancement into the test block (“stall” or “strip”) within the first five revolutions, as indicated by a rapid loss of torsional resistance and an unchanging (“flatlined”) axial displacement. When a specimen stalls, the resumption of the increase in axial force at a rate of 2.0 N/s ( $\pm$ 1.0 N/s) is acceptable to once again achieve self-tap provided: (1) the secondary, maximum axial force is reported as the “self-tap force”; (2) the specimen completes five revolutions after the secondary self-tap; and (3) the specimen is indicated as “stalled” or “stripped” in the Comments section of the test report. Any specimen that stalls more than once shall be considered invalid.

### A4.5 Report

A4.5.1 Report the following information for each specimen tested (all standard units for reporting shall be in SI units):

A4.5.1.1 *Screw Identification*—Reference any applicable ASTM or ISO specification that may apply to the specimen. If specifications do not exist, provide head form, thread form, major and minor diameter, thread pitch, overall screw length, head and shank (unthreaded portion of the screw excluding the head) length, and type of screw point.



**FIG. A4.2 Typical Test Method Output**

A4.5.1.2 Screw chemical composition.

A4.5.1.3 Ultimate tensile strength.

A4.5.1.4 Surface finish.

A4.5.1.5 Self-tap force.

A4.5.1.6 Comments regarding unique testing conditions or specimen occurrences.

A4.5.1.7 Insertion test speed if outside the range specified.

A4.5.1.8 ~~Test Block Material Description—Specification~~ **Test Block Material Description—Specification F1839** grade. (Note that Specification **F1839** is intended to simulate cancellous bone. However, self-tapping screws must penetrate cortical bone as well. Therefore, alternative material(s) may be used to challenge the test specimens provided a material choice justification is included in the test report.) For material that does not conform to Specification **F1839**, provide:

- (1) Trade name.
- (2) Composition.
- (3) Density.
- (4) Tensile strength.
- (5) Compression strength.
- (6) Shear strength.

#### **A4.6 Precision and Bias**

A4.6.1 Data establishing the precision and accuracies to be expected from this test method will be obtained within five years.

## **A5. SPECIFICATIONS FOR HA AND HB METALLIC MEDICAL BONE SCREWS**

### **A5.1 Screw Classification**

A5.1.1 There are a large variety of medical bone screws currently in use. They may be classified by the definitions provided in Section 3. This specification includes the following types of screws with a solid head and a solid core:

A5.1.1.1 *Type HA*—Shallow, asymmetrical buttress thread, deep screw head, and spherical undersurface of head.

A5.1.1.2 *Type HB*—Deep, asymmetrical buttress thread, shallow screw head, and spherical undersurface of head.

### **A5.2 Screw and Thread Form Dimensions**

A5.2.1 There are many types of metallic bone screw designs available, so a complete list of dimensions and tolerances for all screws covered by this specification is unfeasible. This specification specifies dimensions and tolerances for two types of screws that are classified in 4.1. Screws conforming to this specification, and designated with either the HA or HB classification shall be fabricated in accordance with the dimensions and tolerances in this Annex in accordance with the following requirements.

A5.2.1.1 *Type HA:*

- (1) *Screw Dimensions*—The dimensions of HA screws are given in **Table A5.1** and **Fig. A5.1**.
- (2) *Screw Thread*—The dimensions of the threads of HA screws are given in **Table A5.2** and **Fig. A5.2**.

A5.2.1.2 *Type HB:*

- (1) ~~*Screw Dimensions*~~—~~*The Dimensions*~~—The dimensions of HB screws are given in **Table A5.3** and **Fig. A5.3**.
- (2) *Screw Thread*—The dimensions of the threads of HB screws are given in **Table A5.4** and **Fig. A5.4**.

### A5.3 Drive Connections

A5.3.1 Screws conforming to this specification, and designated with either the HA or HB classification shall be fabricated with the following drive connections in accordance with the dimensions and tolerances found in Annex A7.

A5.3.1.1 *Type HA*—Hexagonal recess for accepting the Specification F116 Type IV—Hexagonal bit.

A5.3.1.2 *Type HB*—Hexagonal recess for accepting the Specification F116 Type IV—Hexagonal bit.

### A5.4 Performance Requirements

A5.4.1 Screws that meet the dimensional requirements of the HA and/or HB screws in A5.2 shall also meet the following mechanical performance requirements.

A5.4.1.1 *Maximum Torque:*

(1) A minimum of five screws for a particular type and size shall be tested in accordance with the test methods described in Annex A1, with five threads exposed in the gage length.

(2) The maximum torque of all screws within the sample of screws from a particular type and size of screw shall meet or exceed the requirements provided in Table A5.5.

A5.4.1.2 *Breaking Angle:*

(1) A minimum of five screws for a particular type and size shall be tested in accordance with the methods described in Annex A1, with five threads exposed in the gage length.

(2) The breaking angle of all screws within the sample of screws from a particular type and size of screw shall meet or exceed the requirements provided in Table A5.5.

TABLE A5.1 Dimensions for HA Screws (Fig. A5.1)

Screw Type and Size	Head Diameter, $d_2$		Head Height, $k$	Bottom Head Radius, $r_1$		Top Head Radius, $r_2$	Tip Radius, $r_3$	Screwdriver Size <sup>A</sup>
HA 1.5	3.00	+0.00 -0.10	1.6	1.750	+0.000 -0.075	1.5	0.3	1.5
HA 2.0	4.00	+0.00 -0.10	1.9	2.250	+0.000 -0.075	2.0	0.4	1.5
HA 2.7	5.00	+0.00 -0.15	2.3	2.750	+0.000 -0.075	2.5	0.4	2.5
HA 3.5	6.00	+0.00 -0.15	2.6	3.250	+0.000 -0.075	2.5	1.0	2.5
HA 4.0	6.00	+0.00 -0.15	2.4	3.250	+0.000 -0.075	2.5	1.0	2.5
HA 4.5	8.00	+0.00 -0.15	4.6	4.250	+0.000 -0.075	2.5	1.0	3.5
HA 5.0	8.00	+0.00 -0.15	4.6	4.250	+0.000 -0.075	2.5	1.0	3.5

<sup>A</sup> Type IV hexagonal screwdriver bit as specified in Specification F116.

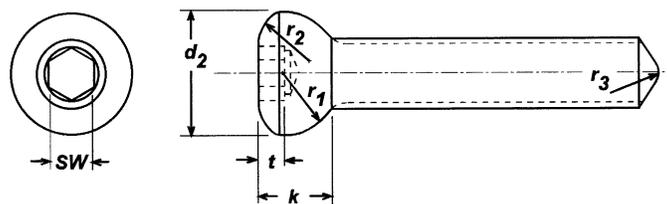


FIG. A5.1 Schematic of HA Screw Dimensions (Table A5.1)

TABLE A5.2 Dimensions for HA Screw Thread (Fig. A5.2)

Screw Type and Size	Thread Diameter, $d_1$		Core Diameter, $d_5$		Crest Width, $e$	Thread Pitch, $P$	Leading Edge Radius, $r_4$	Trailing Edge Radius, $r_5$	Leading Edge Angle, $\alpha$	Trailing Edge Angle, $\beta$
HA 1.5	1.50	+0.00 -0.15	1.10	+0.00 -0.10	0.1	0.5	0.3	0.1	35	3
HA 2.0	2.00	+0.00 -0.15	1.30	+0.00 -0.10	0.1	0.6	0.4	0.1	35	3
HA 2.7	2.70	+0.00 -0.15	1.90	+0.00 -0.15	0.1	1.0	0.6	0.2	35	3
HA 3.5	3.50	+0.00 -0.15	2.40	+0.00 -0.15	0.1	1.25	0.8	0.2	35	3
HA 4.0	4.00	+0.00 -0.15	2.90	+0.00 -0.15	0.1	1.5	0.8	0.2	35	3
HA 4.5	4.50	+0.00 -0.15	3.00	+0.00 -0.15	0.1	1.75	1.0	0.3	35	3
HA 5.0	5.00	+0.00 -0.15	3.50	+0.00 -0.15	0.1	1.75	1.0	0.3	35	3

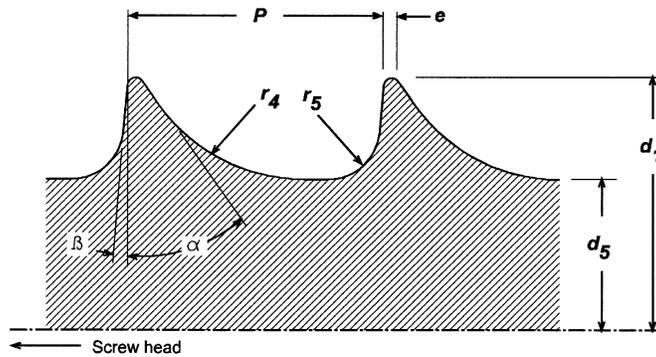


FIG. A5.2 Schematic of HA Screw Thread Dimensions (Table A5.2)

TABLE A5.3 Dimensions for HB Screws (Fig. A5.3)

Screw Type and Size	Head Diameter, $d_2$		Shaft Diameter, $d_4$		Head Height, $k$	Bottom Head Radius, $r_1$	Top Head Radius, $r_2$	Screwdriver Size <sup>A</sup>
HB 4.0	6.00	+0.00 -0.15	2.40	+0.00 -0.15	2.9	3.250	+0.000 -0.075	2.5
HB 6.5	8.00	+0.00 -0.15	4.50	+0.00 -0.15	4.6	4.250	+0.000 -0.075	3.5

<sup>A</sup> Type IV hexagonal screwdriver bit as specified in Specification F116.

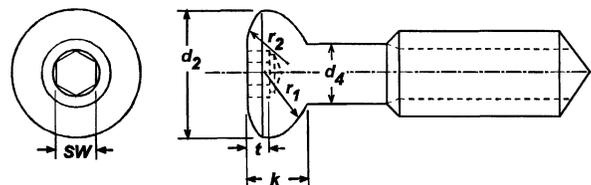


FIG. A5.3 Schematic of HB Screw Dimensions (Table A5.3)

TABLE A5.4 Dimensions for HB Screw Thread (Fig. A5.4)

Screw Type and Size	Thread Diameter, $d_1$		Core Diameter, $d_5$		Crest Width, $e$	Thread Pitch, $P$	Leading Edge Radius, $r_4$	Trailing Edge Radius, $r_5$	Leading Edge Angle, $\alpha$	Trailing Edge Angle, $\beta$
HB 4.0	4.00	+0.00 -0.15	1.90	+0.00 -0.15	0.1	1.75	0.8	0.3	25	5
HB 6.5	6.50	+0.00 -0.15	3.00	+0.00 -0.15	0.2	2.75	1.2	0.8	25	5

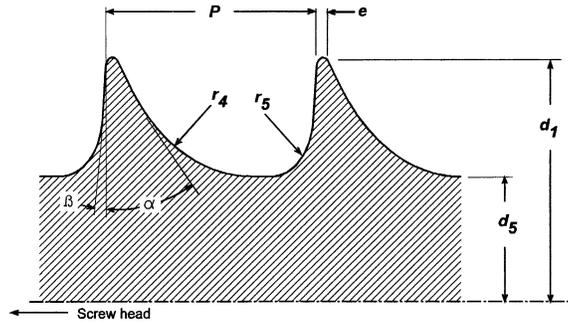


FIG. A5.4 Schematic of HB Screw Thread Dimensions (Table A5.4)

TABLE A5.5 Torsional Strength and Breaking Angle Requirements for HA and HB Screws

Type and Size	Minimum Acceptable Values	
	Torque, Nm†	Breaking Angle, °, with Five Exposed Threads
HA 1.5	0.2	150
HA 2.0	0.35	150
HA 2.7	1.0	180
HA 3.5	2.3	180
HA 4	4.0	180
HA 4.5	4.4	180
HA 5	5.5	180
HB 4	1.3	90
HB 6.5	6.2	90

†Unit of measure was editorially corrected.

## A6. SPECIFICATIONS FOR HC AND HD METALLIC MEDICAL BONE SCREWS

### A6.1 Screw Classification

A6.1.1 There are a large variety of medical bone screws currently in use. They may be classified by the definitions provided in Section 34. This specification includes the following types of screws with a solid head and a solid core:

A6.1.1.1 *Type HC*—Conical undersurface of head, symmetrical thread.

A6.1.1.2 *Type HD*—Conical undersurface of head, asymmetrical thread.

### A6.2 Screw and Thread Form Dimensions

A6.2.1 There are many types of metallic bone screw designs available, so a complete list of dimensions and tolerances for all screws covered by this specification is unfeasible. This specification specifies dimensions and tolerances for two types of screws that are classified in 4.1. Screws conforming to this specification, and designated with either the HC or HD classification shall be fabricated in accordance with the dimensions and tolerances in this Annex in accordance with the following requirements.

#### A6.2.1.1 *Type HC:*

- (1) *Screw Dimensions*—The dimensions of HC screws are given in [Table A6.1](#) and [Fig. A6.1](#).
- (2) *Screw Thread*—The dimensions of the threads of HC screws are given in [Table A6.2](#) and [Fig. A6.2](#).

#### A6.2.1.2 *Type HD:*

- (1) *Screw Dimensions*—The dimensions of HD screws are given in [Table A6.3](#) and [Fig. A6.3](#).
- (2) *Screw Thread*—The dimensions of the threads of HD screws are given in [Table A6.4](#) and [Fig. A6.4](#).

### A6.3 Drive Connections

A6.3.1 Screws conforming to this specification, and designated with either the HC or HD classification shall be fabricated with the following drive connections in accordance with the dimensions and tolerances found in [Annex A7](#).

#### A6.3.1.1 *Type HC:*

- (1) Single-slot recess for accepting the Specification [F116](#) Type I—single-slot bit.
- (2) Cruciate recess for accepting the Specification [F116](#) Type II—cruciate-slot bit.
- (3) Combined cruciate-slot and cross-slot recess for accepting either the Specification [F116](#) Type II—cruciate-slot or Type III—cross-slot (modified Phillips) bits.

A6.3.1.2 *Type HD*—Combined single-slot and cross-slot recess for accepting either the Specification [F116](#) Type I—single-slot or Type III—cross-slot (modified Phillips) bits.

### A6.4 Performance Requirements

A6.4.1 Screws that meet the dimensional requirements of the HC or HD screws in [A6.2](#) shall be tested to document the following mechanical performance characteristics.

A6.4.1.1 *Torsional strength*—A minimum of five screws for a particular type and size shall be tested in accordance with the methods described in [Annex A1](#), with five threads exposed in the gage length.

A6.4.1.2 *Breaking angle*—A minimum of five screws for a particular type and size shall be tested in accordance with the methods described in Annex A1, with five threads exposed in the gage length.

TABLE A6.1 Dimensions for HC Screws (Fig. A6.1)

Screw Type and Size	Shaft Diameter, $d_1$	Head Diameter, $d_2$	Head Height, $h$	Unthreaded Length, $x$	Top Head Radius, $r_2$
HC 2.9	2.9	4.62 – 6.1	1.5 - 2	1.6	5
HC 3.5	3.5	5.8 – 6.5	1.5 - 2	1.6	6.35
HC 3.9	3.9	5.8 – 6.5	1.5 - 2	1.6	6.35
HC 4.2	4.2	5.8 – 6.5	1.5 - 2	1.6	6.35

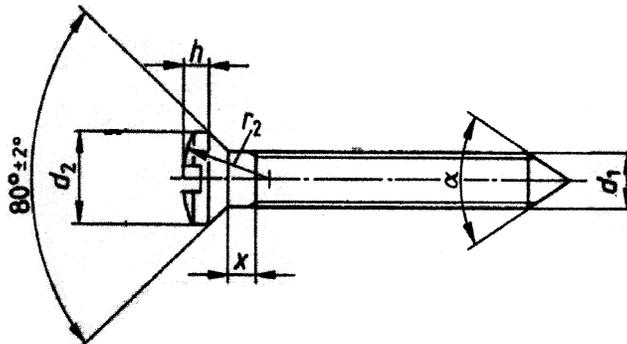


FIG. A6.1 Schematic of HC Screw Dimensions (Table A6.1)

TABLE A6.2 Dimensions for HC Screw Thread (Fig. A6.2)

Screw Type and Size	Thread Diameter, $d_1$	Core Diameter, $d_5$	Thread Pitch, $P$	c max
HC 2.9	2.79 – 2.90	2.03 – 2.18	1.06	0.1
HC 3.5	3.43 – 3.53	2.51 – 2.64	1.27	0.1
HC 3.9	3.78 – 3.91	2.77 – 2.92	1.27	0.1
HC 4.2	4.09 – 4.22	2.95 – 3.25	1.27	0.1

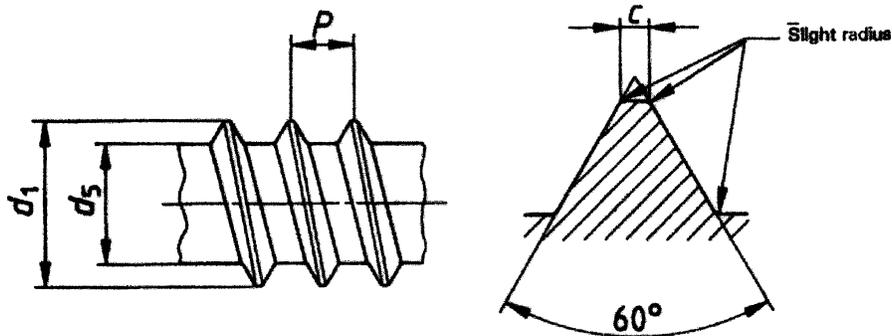


FIG. A6.2 Schematic of HC Screw Thread Dimensions (Table A6.2)

## A7. SPECIFICATIONS FOR METALLIC BONE SCREW DRIVE CONNECTIONS

### A7.1. Scope

A7.1.1 This annex specifies the requirements for a variety of drive connections that can be implemented in metallic medical bone screws. The screw's drive connection supplies the interconnection that is typically used in orthopedic surgery for inserting and removing bone screws.

TABLE A6.3 Dimensions for HD Screws (Fig. A6.3)

Screw Type and Size	Shaft Diameter, $d_s$	Head Diameter, $d_2$	Head Height, $H$	Unthreaded Length, $x$	Head Top Radius, $r_1$
HD 4.0	4.0	6.75 – 7.35	1.8 – 2.1	1.6	6.35
HD 4.5	4.5	6.75 – 7.35	1.8 – 2.1	1.6	6.35

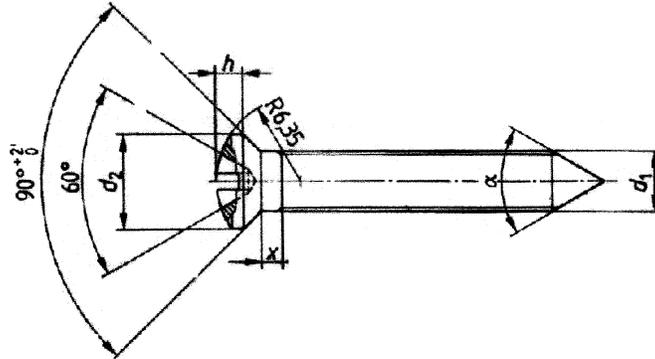


FIG. A6.3 Schematic of HD Screw Dimensions (Table A6.3)

TABLE A6.4 Dimensions for HD Screw Thread (Fig. A6.4)

Screw Type and Size	Thread Diameter, $d_1$	Core Diameter, $d_5$	Crest Width, $e$	Thread Pitch, $P$	Leading Edge Angle, $\alpha$	Trailing Edge Angle, $\beta$
HD 4	3.97 – 4.03	2.89 – 2.95	0.1	1.59	45	10
HD 4.5	4.47 – 4.53	2.89 – 2.95	0.1	2.18	45	10

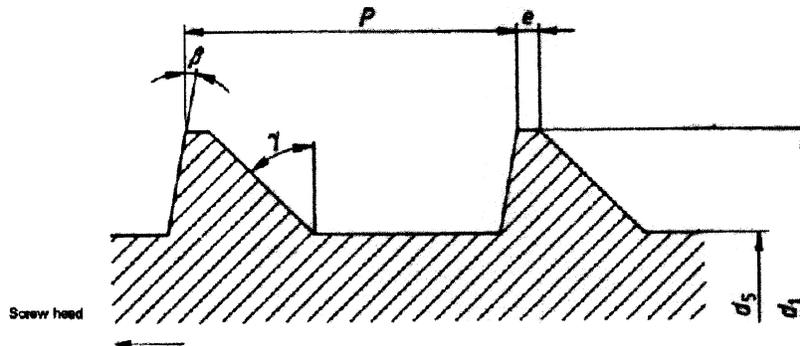


FIG. A6.4 Schematic of HD Screw Thread Dimensions (Table A6.4)

## A7.2 Classification

A7.2.1 There are many methods that can be used to classify medical bone screws. The majority of the methods currently being used in the medical industry can be found in Section 3 of this specification. An additional characteristic not covered in Section 3 is the bone screw’s drive connection. This specification describes the following drive connections that are compatible with the noted screwdriver bits.

A7.2.1.1 *Single-Slot*—This drive connection is illustrated in Fig. A7.1. Screws manufactured with this drive connection can be driven with the Specification F116 Type I—single-slot bit or the ISO 8319/2 single-slot screwdriver bit.

A7.2.1.2 *Cross-Recessed*—This drive connection is illustrated in Fig. A7.2. Screws manufactured with this drive connection can be driven with the Specification F116 Type III—cross-slot (modified Phillips) bit or the ISO 8319/2 cross-recessed head screwdriver bit.

A7.2.1.3 *Combined Single-Slot and Cross-Recessed*—This drive connection is illustrated in Fig. A7.3. Screws manufactured with

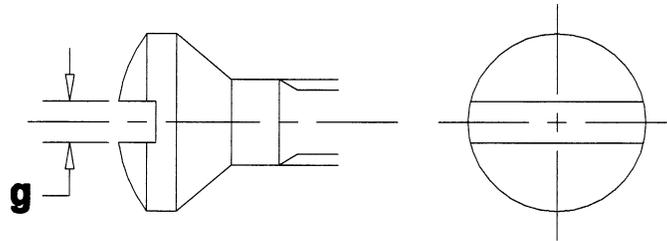


FIG. A7.1 Schematic of Screw with Single-Slot Drive Connection (Table A7.1)

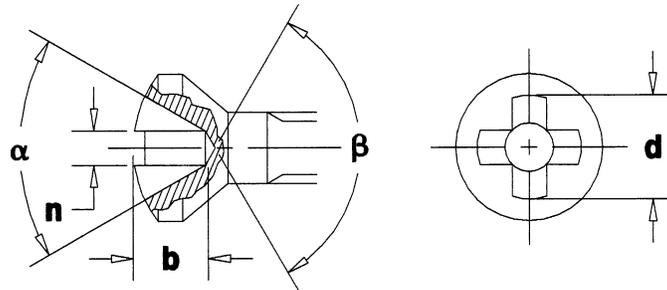


FIG. A7.2 Schematic of Screw with Cross-Recessed Drive Connection (Table A7.2)

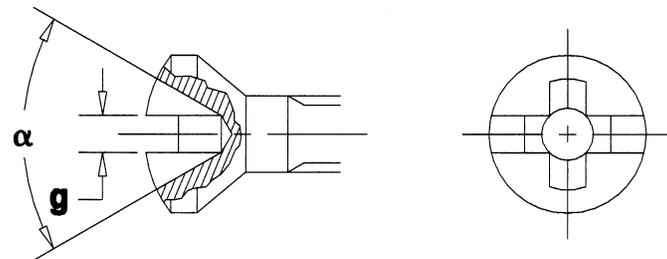


FIG. A7.3 Schematic of Screw with Combined Single-Slot and Cross-Recessed Drive Connection (Table A7.3)

this drive connection can be driven with the F116 Type I—single-slot bit, Specification F116 Type III—cross-slot (modified Phillips) bit, the ISO 8319/2 single-slot screwdriver bit, or the ISO 8319/2 cross-recessed head screwdriver bit.

A7.2.1.4 *Cruciate-Slot*—This drive connection is illustrated in Fig. A7.4. Screws manufactured with this drive connection can be driven with the Specification F116 Type I—single-slot bit, Specification F116 Type II—cruciate-slot bit, the ISO 8319/2 single-slot screwdriver bit, or the ISO 8319/2 cruciate-slot screwdriver bit.

A7.2.1.5 *Combined Cruciate-Slot and Cross-Recessed*—This drive connection is illustrated in Fig. A7.5. Screws manufactured with this drive connection can be driven with the Specification F116 Type I—single-slot bit, F116 Type II—cruciate-slot bit, the Specification F116 Type III—Cross-slot (modified Phillips) bit, the ISO 8319/2 single-slot screwdriver bit, ISO 8319/2 cruciate-slot screwdriver bit, or the ISO 8319/2 crossed-recessed head screwdriver bit.

A7.2.1.6 *Hexagonal*—This drive connection is illustrated in Fig. A7.6. Screws manufactured with this drive connection can be driven with the Specification F116 Type IV—hexagonal or the ISO 8319/1 hexagonal screwdriver bit.

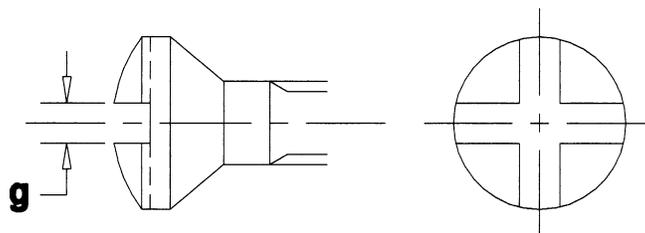


FIG. A7.4 Schematic of Screw with Cruciate-Slot Drive Connection (Table A7.4)

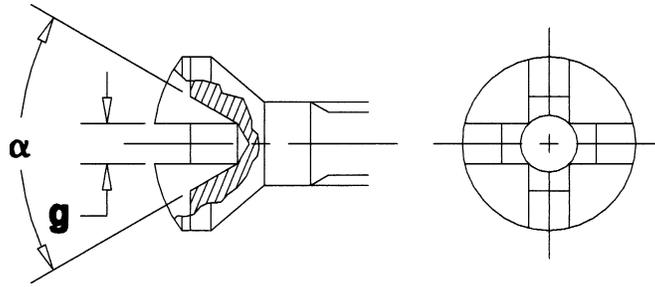


FIG. A7.5 Schematic of Screw with Combined Cruciate-Slot and Cross-Recessed Drive Connection (Table A7.5)

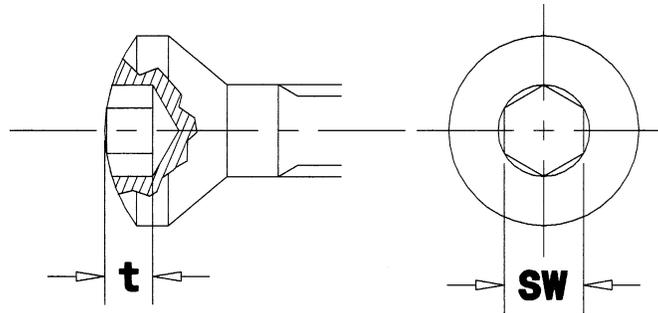


FIG. A7.6 Schematic of Screw with Hexagonal Drive Connection (Table A7.6)

A7.2.1.7 *Square*—This drive connection is illustrated in Fig. A7.7. At this time no standard screwdriver bit is specified for this drive connection. Screws manufactured with this drive connection can be driven with square drive screwdriver bits.

A7.2.1.8 *Hexalobe*—This drive connection is illustrated in Fig. A7.8. At this time no standard screwdriver bit is specified for this drive connection. Screws manufactured with this drive connection can be driven with hexalobe (six-lobe) screwdriver bits. bits that conform to ISO 10664 Standard for Hexobular internal driving feature for bolts and screws..

### A7.3 Dimensions

A7.3.1 Medical bone screws conforming to this specification are as follows:

A7.3.1.1 *Single-Slot*—The dimensions for this drive connection are given in Table A7.1 and Fig. A7.1.

A7.3.1.2 *Cross-Recessed*—The dimensions for this drive connection are given in Table A7.2 and Fig. A7.2.

A7.3.1.3 *Combined Single-Slot and Cross-Recessed*—The dimensions for this drive connection are given in Table A7.3 and Fig. A7.3. The maximum depth of the recess shall be such that the torque strength of the screw is unaffected.

A7.3.1.4 *Cruciate-Slot*—The dimensions for this drive connection are given in Table A7.4 and Fig. A7.4.

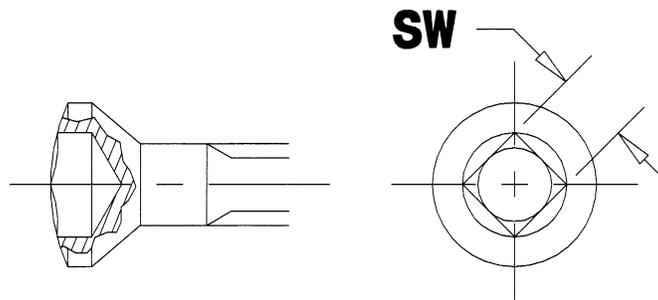


FIG. A7.7 Schematic of Screw with Square Drive Connection (Table A7.7)

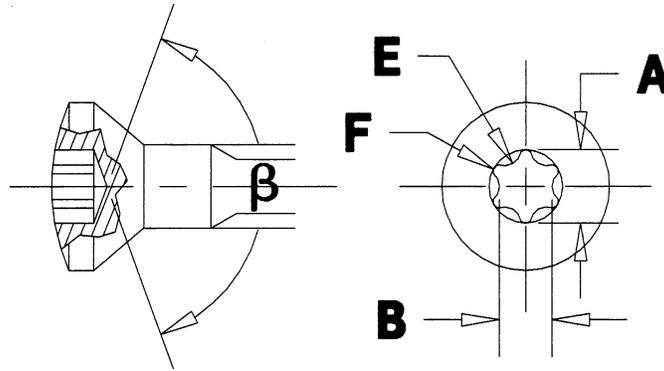


FIG. A7.8 Schematic of Screw with Hexalobe Drive Connection (Table A7.8)

TABLE A7.1 Single-Slot Drive Connection Dimensions (Fig. A7.1)

Screw Type and Size	Nominal Diameter, mm	Slot Width, g, mm
HC 2.9	2.9	1.25 - 1.4
HC 3.5	3.5	1.25 - 1.4
HC 3.9	3.9	1.25 - 1.4
HC 4.2	4.2	1.25 - 1.4

TABLE A7.2 Cross-Recessed Drive Connection Dimensions (Fig. A7.2)

Nominal Diameter, mm	$d$	$b$ max	$n$
4.5	5	3.8	1.4

TABLE A7.3 Combined Single-Slot and Cross-Recessed Drive Connection Dimensions (Fig. A7.3)

Screw Type and Size	Slot Width, g, mm	Slot Angle, $\alpha$ , °
HD 4.0	1.25 - 1.4	60
HD 4.5	1.25 - 1.4	60

TABLE A7.4 Cruciate-Slot Drive Connection Dimensions (Fig. A7.4)

Screw Type and Size	Nominal Diameter, mm	Slot Width, g, mm
HC 3.5	3.5	1.25 - 1.4
HC 3.9	3.9	1.25 - 1.4
HC 4.2	4.2	1.25 - 1.4

A7.3.1.5 *Combined Cruciate-Slot and Cross-Recessed*—The dimensions for this drive connection are given in Table A7.5 and Fig. A7.5. The maximum depth of the recess shall be such that the torque strength of the screw is unaffected.

A7.3.1.6 *Hexagonal*—The dimensions for this drive connection are given in Table A7.6 and Fig. A7.6.

A7.3.1.7 *Square*: The dimensions for this drive connection are given in Table A7.7 and Fig. A7.7. The maximum depth of the recess shall be such that the torque strength of the screw is unaffected.

TABLE A7.5 Combined Cruciate-Slot and Cross-Recessed Drive Connection Dimensions (Fig. A7.5)

Screw Type and Size	Nominal Diameter, mm	Slot Width, g, mm	Slot Angle, $\alpha$ , °
HC 3.5	3.5	1.25 - 1.4	60
HC 3.9	3.9	1.25 - 1.4	60
HC 4.2	4.2	1.25 - 1.4	60

**TABLE A7.6 Hexagonal Drive Connection Dimensions (Fig. A7.6)**

Screw Type and Size	Nominal Diameter, mm	Screwdriver Bit Size	SW, mm	t, mm
HA 1.5	1.5	1.5	1.507 +0.040 -0.000	0.8
HA 2.0	2.0	1.5	1.507 +0.040 -0.000	1.0
HA 2.7	2.7	2.5	2.507 +0.040 -0.000	1.2
HA 3.5	3.5	2.5	2.507 +0.040 -0.000	1.5
HA 4.0	4.0	2.5	2.507 +0.040 -0.000	1.5
HA 4.5	4.5	3.5	3.510 +0.048 -0.000	2.8
HA 5.0	4.5	3.5	3.510 +0.048 -0.000	2.8
HB 4.0	4.0	2.5	2.507 +0.040 -0.000	1.5
HB 6.5	6.5	3.5	3.510 +0.048 -0.000	2.8

**TABLE A7.7 Square Drive Connection Dimensions (Fig. A7.7)**

Screw Size	SW, mm
1.0	0.7
1.5	1.0
2.0	1.27

A7.3.1.8 *Hexalobe*—The dimensions for this drive connection are given in [Table A7.8](#) and [Fig. A7.8](#). The maximum depth of the recess shall be such that the torque strength of the screw is unaffected.

## APPENDIX

### (Nonmandatory Information)

#### X1. METALLIC BONE SCREWS

X1.1 This specification is intended to provide useful and consistent information related to the performance, terminology, requirements for materials, finish and marking considerations, and care and handling of metallic bone screws. It includes the terms and requirements of Specification F543-98. This specification also includes the test methods that were previously published separately as Specifications F117, F1622, and F1691.<sup>6</sup>

X1.2 Materials which have been found acceptable for metallic bone screws includes:

X1.2.1 Stainless steel alloy (Specification F138).

<sup>6</sup> Discontinued; see 2000 *Annual Book of ASTM Standards*, Vol 13.01. Replaced May 2001 by Specification and Test Methods F543.

**TABLE A7.8 Hexalobe Drive Connection Dimensions (Fig. A7.8)**

Drive Size	A, (mm)	B, (mm)	E Radius, (mm)	F Radius, (mm)	β, (°)	Screwdriver Bit Size
4	1.35	0.97	0.28	0.12	140	4
5	1.47	1.07	0.30	0.14	140	5
6	1.75	1.27	0.36	0.16	140	6
8	2.4	1.75	0.49	0.22	140	8
10	2.8	2.05	0.57	0.25	140	10
15	3.35	2.40	0.69	0.30	140	15
20	3.95	2.85	0.83	0.34	140	20
25	4.50	3.25	0.89	0.40	140	25
30	5.60	4.05	1.16	0.48	140	30

X1.2.2 Nitrogen-strengthened stainless steel alloy (Specifications [F1314](#) and [F1586](#))

X1.2.3 Unalloyed titanium (Specification [F67](#)).

X1.2.4 Titanium-aluminum-vanadium alloy (Specifications [F136](#), [F620](#), and [F1472](#)).

X1.2.5 Titanium-aluminum-niobium alloy (Specification [F1295](#)).

X1.2.6 Titanium-niobium-zirconium alloy (Specification [F1713](#)).

X1.2.7 Cobalt-chromium-molybdenum alloy (Specifications [F799](#) and [F1537](#)).

X1.2.8 Titanium-molybdenum-zirconium-iron alloy (Specification [F1813](#)).

X1.2.9 Titanium-molybdenum-zirconium-iron alloy (Specification [F2066](#)).

X1.3 Dimensional requirements are provided for four specific types of bone screws. These screws, specified here as Specification F543 Types ~~HA~~, HA and HB, HC, and HD are dimensionally similar to those specified in ISO 5835 and ISO 9268. The dimensions and performance of these types of screws are specified because they have achieved widespread clinical use and are offered by several manufacturers. Standardization of the dimensions and tolerances of the key features of these screws is intended to allow the implants from one manufacturer to be used with the associated instruments (taps, drills, and so forth) from different manufacturers and serve as a baseline for future screw products. This may benefit the surgeon and patient by aiding the identification of the appropriate instrumentation for the implantation and removal of screws by the operating room staff.

X1.4 Performance requirements are provided for two specific types of bone screws. Those that have a solid core and a spherical head, specified here as Specification F543 Type HA and HB, ~~and~~ have performance specifications developed from those specified in ISO 6475. Standardization of the performance requirements and harmonization of these requirements with the similar screws described in ISO standards is intended to facilitate the ~~approval~~approval to market for manufacturers declaring conformity to either or both standards.

X1.5 This specification provides minimum performance limits for the torsional properties of bone screws and a uniform test procedure by which these limits can be determined. The parameters specified in this specification are breaking torque and breaking angle.

X1.5.1 The breaking torque is intended to be a measure of the screw's strength. Torque was determined to be the critical parameter in the insertion of screws into a uniform medium. Unpublished test reports indicated that a screw could experience both torsional and tensile forces when inserted into a uniform medium. If the screw was inserted until it ruptured, then the torsional forces appear to dominate over the tensile forces. Therefore, tensile forces were neglected in analyzing screw strength.

X1.5.2 The breaking angle is a measure of the screw's ductility. For example, a screw that has a breaking angle of 360° is more ductile than one with the same design that breaks at 120° under the same test conditions. Since this parameter does not represent the point at which the screw loses its elastic properties, a torsional yield measurement was devised. This point is intended to present an approximate measure of the torque at which the screw loses its elastic properties. The task force decided that an offset method with a 2° angle offset method was considered to yield the most consistent results.

X1.5.3 The breaking force test method provides a consistent measurement method for fully threaded bone screws. For partially threaded screws, the length of the unthreaded portion of the screw and the threaded portion can vary considerably among different types of screws. Because of this variation, no exact method of fixation is required. Suggestions are made to grip enough threads to hold the screw in a fixed position with possibly one or more thread(s) exposed. If this condition is not possible, then all threads must be gripped. In any case, the experiment is required to record the gage length and the gripping length.

X1.5.4 If an axial force is necessary to engage the screwdriver in the screw head, the value of this force ~~is to~~ shall be determined by the operator. The force should be the minimum needed to engage the screwdriver bit with the screw head.

X1.6 This specification provides a uniform test procedure for measuring the insertion and removal torque of bone screws in a specified medium. This specification can thus provide a measure of the uniformity of the products tested or compare the insertion and removal torque among similar or dissimilar screws.

X1.6.1 The test method specifies that the bone screw be driven at a rate of 1 to 5 r/min into the test block. The rate specified in the original Test Method F117<sup>6</sup> standard was selected and based upon the limitations of torsion test systems when the standard was originally developed. Faster driving rates (an order of magnitude greater at 30 r/min) can better simulate the clinical situation for hand-driven screws. Therefore, the user may choose to use higher screw-driving rates, as long as the selected rate is justified and reported. All comparative test methods must be performed at the same driving rate.

X1.6.2 During the development of this test method, the committee noted the need to test sterilized screws. *Infection Control and Sterilization Technology*, V4, No 8 p12, August 1998 reported differences in the driving torque when sterilized and unsterilized screws were tested.

X1.7 This specification provides a uniform test procedure for measuring the axial pullout strength of bone screws from a specified medium. This specification can provide a measure of the uniformity of the products tested or compare the pullout strength among similar or dissimilar screws.

X1.8 During the 2011 periodic review of the standard, the subcommittee received comments from members noting that Specification F543 did not include manufacturing tolerances for the dimensions in the specifications for Type V Square and Type VI Hexalobe screwdriver connections. The subcommittee established that there are no published tolerances for the Type V Square connection. However, a standard relevant to Type VI Hexalobe was identified (ISO 10664) and is included as a reference. The subcommittee believes that deletion of the information on these connections from the standard will detract from the value of the standard as a whole.

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